| Time Au 08:30-09:00 | Aug. 2 | | | | | | | | | AC-ACA | 2025 Techn | ical and Socia | al Programn | ne at a Gla | ance | | | | | | | | | |
|----------------------------|-------------|--|---|---|---|-------------------------------------|--|---|---|--|---|---|---|--|--|--|---------------------------------|--|--|---|--|---|---|--------|
| 08:30-09:00 | | Aug. 3 | | | | | | | Aug. 4 | | | | | | | Aug. 5 | | | | | | | | Aug. 6 |
| | | Grand Ballroom 2 & 3: Opening Ceremony | | | | | | | Semi-Plenary talk 1 Dynamics and Control of Smart Structures for Space Applications Space Applications 鸟群智能激发 | | | | 授 北京航空航天大学 | | Function Room 1: Poster | Function Room 1 | Function Room 2 | Parallel Function Room 3 | Meeting Room | Grand Ballroom 2 | Grand Ballroom 3 | | | |
| 09:00-09:30 | | Grand Ballroom 2 & 3 Plenary talk 1: The Future in Space: Smarter, Sma | | | | aller and More Grand Ballroom Foye | | F | Aeros | Semi-Plenary ta space Control E Castaldi, Univer Italy | | 特邀报告 2 基于全驱系统方法的无退绕航天器姿态控制 陈立群教授 哈尔滨工业大学 (深圳) | | | Session & Grand Ballroom Foyer: | I Autonomous | Aircraft Dynamics, | I Resilient and | I Artificial Intelligence- Based | I FAS | I Spacecraft | VIP Room: Excellent Thesis Defense | Grand Ballroom Foyer: Exhibition Booths | |
| 09:30-09:45 | <u></u> | Cooperative Satellites Prof. Klaus Schilling Center for Telematics (ZfT), Wuerzburg, Germany | | | | | Exhibition Booths | | Semi-Plenary talk 3 Key Technologies of UAV-USV Cooperation System for Maritime Search and Rescue Prof. Weidong Zhang, Shanghai Jiao Tong University, China | | | 特邀报告 3 空间科学极限探测任务中的控制技术 及前沿进展 张永合研究员 中国科学院微小卫星创新研究院 | | | Exhibition Booths | Navigation and Control of Deep Space Probes | Navigation, Guidance | Cooperative Guidance and Control of Aerial Vehicles | Attitude- Orbit Control for Multiple Spacecraft Systems | Theory and Applications in Aerospace Control | Advanced Control for On- orbit Complex Missions | | | Tours |
| 09:45-10:15 | / | | Group Pl | hoto Session | n (Grand Ball | room); Session | n break | | | | | | | | Sess | Session break | | | | | | | | |
| | | Grand Ballroom 2 & 3 Plenary talk 2: Optimal Solar Sail Control for Launching into Artificial Periodic Orbits near L2 of Earth-Moon System Prof. Olga Leonardovna Starinova Samara National Research University, Russia | | | | | | | | Parallel | Sessions 6-11 | | | | II | II | II | II | II | II | | | | |
| 10:15-11:00 | | | | | | | Grand Ballroom Foyer: Exhibition Booths | VIP Room Guidance | Function Room 2 | Function Room 3 | Meeting Room | Grand Ballroom 2 | Grand Ballroom 3 | allroom 3 Advanced secries and oplications Very Low arth Orbit Room 1: Poster Session & Grand Ballroom Foyer: Exhibition | Autonomous Navigation and Control of Deep Space Probes Aircraft Dynamics, Navigation Guidance and Control | Resilient and | Artificial Intelligence- | FAS | Spacecraft | VIP Room: | Grand Ballroom | | | |
| 11:00-11:45 | | Grand Ballroom 2 & 3 Plenary talk 3: On Key Technologies for Spacecraft Intelligent Autonomous Control and Application Prospects Prof. Yongchun Xie Beijing Institute of Control Engineering (BICE), China | | | | | | | and Control for High- Speed Flight in Trans- Domain Complex Environment | Space Intelligent Equipment: Technologies and Applications | Advanced Propulsion | Space Debris Mitigation | | | | Advanced Theories and Applications of Very Low Earth Orbit Spacecraft | Navigation, Guidance | Cooperative Guidance and Control of Aerial Vehicles | Based Attitude- Orbit Control for Multiple Spacecraft Systems | Theory and Applications in Aerospace Control | Advanced Control for On- orbit Complex Missions | Excellent Thesis Defense | Foyer: Exhibition Booths | |
| 12:00-14:00 | | | | | | | | | | | Grand 1 | Ballroom 1 & Lobby | y Western Restaura | nnt: Lunch | | | | | | | | | | |
| | | Parallel Sessions 1-5 | | | | | | | | | Parallel | Sessions 12-17 | | | | | Parallel Ses | | | ssions 24-27 | | | | |
| | | Function Room 1 | Function Room 2 | Function Room 3 | Grand Ballroom 2 | Grand Ballroom 3 | Grand Ballroom Foyer: Exhibition Booths | | VIP Room | Function Room 2 | Function Room 3 | Meeting Room | Grand Ballroom 2 | Grand Ballroom 3 | Function Room 1: Poster Session & Grand Ballroom Foyer: Exhibition Booths | | Function Function Room 1 Room 2 | | | Function Room 3 | Meeting Room | Grand Ballroom Foyer: Exhibition Booths | | |
| | i Lobby: | Swarm Intelligence in Aerospace Dynamics and Control | Advanced Navigation, Control, and Swarm Coordination for Aircraft Cluster | Advanced Control and Path Planning of Space Robots | Micro- and Nano- Satellites and Education | I Space Traffic Management | | | I Intelligent Autonomous Swarm Perception, Decision- Making, Control, and Applications | Contemporary Advances in AI and Its Application in Aerial Systems | S2: Health Monitoring, Diagnosis, and | I S1: Advanced Control of Large-Scale and Distributed Space Structures S2: Applications of Machine Learning in Rendezvous and Docking as well as Space Operations | Control S2: Space | Advanced Information Fusion Technology for Aerospace Applications | | Advanced Si Making and Aerospace | Control for | Diagnosis, Maintenance, and Digital Simulation of LEO Constellation Satellites | | Large-Scale Constellation Control and Management | Flexible Structure Control for Aerospace | | | 1 |
| 15:30-16:00 Regis | gistration | | | | | | | | Session breal | k | | | | | | Session break | | | | | | | | |
| | | II | II | П | II | II | | | II | II | II | II | II | II | Function | Plenary talk 4: | | Grand Ballroom 2 & 3 Optimal Guidance in Soft-Landing of Chandrayaan-3 Prof. Radhakant Padhi | | | Grand Ballroom Foyer: Exhibition Booths | | | |
| 16:15-17:00 | i | Swarm Intelligence n Aerospace Dynamics and Control | Advanced Navigation, Control, and Swarm Coordination for Aircraft Cluster | control and Path Planning | Micro- and Nano- Satellites and Education | Space Traffic Management | Room: Ba TC F Committee Ex | Grand Ballroom Foyer: Exhibition Booths | Intelligent Autonomous Swarm Perception, Decision- Making, Control, and Application Application Systems Applications | | Control for Complex New Space Missions S2: Health Monitoring, | S1: Advanced Control of Large-Scale and Distributed Space Structures S2: Applications of Machine Learning in Rendezvous and Docking as well as | S1: Spacecraft Collision Threat Prediction and Autonomous Avoidance Control S2: Space Situation | Advanced Information Fusion Technology for Aerospace Applications | Function Room 1: Poster Session & Grand Ballroom Foyer: Exhibition Booths | Indian Institute of Science, India Grand Ballroom 2 & 3 Plenary talk 5: In-Cabin Robots for Space Stations: Research Sta Prof. Lixian Zhang | | | | , India 3 earch Status and ty, China | | | | |
| 17:00-18:00 18:00-20:00 | | | | | | | Grand | Rallroom 1 | 8r I obby West | ern Restaurant: | | Space Operations | Awareness | | | Grand Ballroom 2 & 3: Closing Ceremony Lobby Western Restaurant / Grand Ballroom 1: Farewell Banquet | | | | | | | | |

地址注释: 多功能厅 1—Function Room 1; 多功能厅 2—Function Room 2; 多功能厅 3—Function Room 3; 董事会议室—Meeting Room; 宴会厅 1—Grand Ballroom 1; 宴会厅 2—Grand Ballroom 2; 宴会厅 3—Grand Ballroom 3 贵宾厅—VIP Room; 美食汇西餐厅—Lobby Western Restaurant; 廊厅—Grand Ballroom Foyer.